



Integrating the Geospatial Workplace

# New Features in TerraMatch

## What's New in Terrasolid v014?

### Webinar

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## Draw Observations

- Menu command in tie lines for drawing observation points into design file
- Useful in workflow for solving camera misalignment angles in mobile data:
  1. Solve laser misalignment angles and apply
  2. Find signal markers in laser data
  3. Draw signal markers position in laser data into design file
  4. Collect tie points in images using laser signal marker positions as known xyz points from same drive pass only
  5. Solve camera misalignment angle matching camera to laser data



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## Lever Arm Solution

- **Find Tie Line Match** can solve for lever arm X, Y and Z corrections for mobile scanners
- Written for Velodyne (Topcon) systems with possibly 64 laser heads

Find Tie Line Match

System: Mobile  
Source: Tie line file  
Tie lines: D:\topcon\mission\calibration.til  
Trajectory dir: D:\topcon\trajectory\_scan

Solve for: Whole data set  
Scanners: Solution per scanner  
Correct: All solution sets

Heading shift  Lever X  
 Roll shift  Lever Y  
 Pitch shift  Lever Z

OK Cancel

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## Apply Correction Key-in Parameters

- **Apply Correction** can be run using key-in for automation (another application can send the key-in command)
- **Parameters:**
  - apply=points/project/tiefile/tielines/images
  - trajdir=trajectory\_folder (c:\vt6\trajectory\_scan)
  - project=project\_file (c:\vt6\laser02\vt6.prj)
  - writedir=result\_folder (c:\vt6\laser03)
  - corrections=correction\_file (c:\vt6\calib\fluct\_xyz.tms)
  - run=0/1
- **Example key-in command:**

```
apply correction apply=project/project=g:\vt6\laser06\vt6.prj
/writedir=c:\backup/corrections=g:\vt6\calib\fluct_xyzi.tms/run=1
```

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## Find Rubber Sheet Correction

- Fixes data to match control points using a triangulated correction model for XYZ, XY or Z
- Observations come from tie lines
- Possible last adjustment step for aerial airborne data:
  - Match data internally
  - Match to control using rubber sheet

**Find Rubbersheet Fit**

Source: Active tie lines

Trajectory dir: E:\jyvaskyla\_airborne\trajectory  
Solve: Z  
Expand model: Closest correction

Averaging

Max count: 15 closeby points  
Max distance: 50.0 m  
 Merge final correction points

OK Cancel



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